

()

*

(// : // :)

/

(α^*)

.()

()
 () ()
 () () ()

(ψ_i)
 (S)

$$k(\psi) = k_{fs} e^{\alpha\psi} \quad ()$$

(.)

(\bar{V}_{rp})
 (\bar{V}_{zp})

()

(\bar{V}_g)

(.)

$$Q_s = \left[\left(\frac{2\pi H^2}{C} \right) + \pi \alpha^2 \right] K_{GP} + \frac{2\pi H}{C} \phi_m \quad ()$$

$$K_p = 1.15r \frac{\log \left[h(t_1) + \frac{r}{2} \right] - \log \left[h(t_2) + \frac{r}{2} \right]}{t_2 - t_1} \quad ()$$

()
 () Q_s ()
 a () H

K_p
 r
 t_i $h(t_i)$

C ()

$\frac{H}{a}$

()

()

(K_{fs})

« »

«

»

ϕ_m ()

K_{GP}

$: K_R$

(m/s)

ϕ_m

K_{GP}

H_2

H_1

(m/s) K_{GP}

$: K_L$

(.)

$: \beta \omega$

$K_{GP} K_L$

(.)

$\phi_m K_{GP}$

(.)

()

$$K_S = \frac{CQ}{(2\pi H^2 + C\pi a^2 + \frac{2\pi H}{\alpha_E^*})}$$

(

()

()

()

()

$$\phi_m = \frac{CQ}{(2\pi H^2 + C\pi a^2)\alpha_E^* + 2\pi H}$$

K_{GP}

$: K_S$

α^*

$: \alpha_E^*(m^{-1})$

K_{GP}

()

()

$(\alpha_E^*(m^{-1}))$

α^*

()

SWPI

K_{fs}

()

SWPI

()

$$K_L = \frac{CQ}{(2\pi H^2 + C\pi a^2)}$$

(

(m/s)

K_{GP}

$: K_L$

(r= /)

α^*

K_{GP}

K_L

()

()

K_{GP}

()

$K_R = \beta K_L^\omega$

$\omega \geq 1$

(

$(\alpha^* = \infty)$
 $(\alpha^* =)$

K_{GP}

K_R

$(\omega = 1 \quad \beta = 1)$
 $\omega \quad \beta$
 SAS

PH

(

/ SAS

()

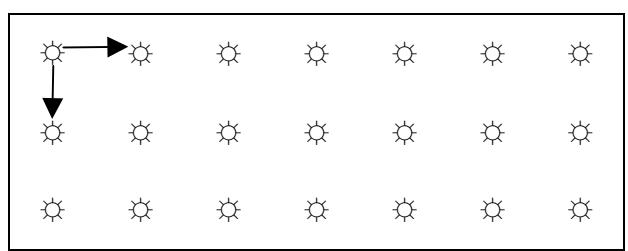
$H_2 \quad H_1$

() a

$C_2 \quad C_1$ ()

() (/
 ($P \leq /$)

()
 () (



... :

/

() α^*

K_L K_{GP}

/

K_p

/ **	/ **	()
/ **	/ **	
/	/	
/	/	(%)
%		* *

-
1. Coefficient of Variation
 2. Standard Deviation
 3. Standard Error

mm/h		m/day		(%)	mm/hr		m/day		
/	/	/	/	/	/	/	/	/	P
/	/	/	/	/	/	/	/	/	PG
/	/	/	/	/	/	/	/	/	S
/	/	/	/	/	/	/	/	/	L
/	/	/	/	/	/	/	/	/	R
				R	L	S	PG		P

α / α^*
 K_S K_{GP}
 α^*

	mm/hr	m/day	
A	/	/	P
B	/	/	L
C	/	/	S
C	/	/	R
C	/	/	PG
	S	PG	P
		R	L

(P ≤ /)

$\alpha^* (m^{-1})$

$\phi_m (m^2 / s)$

$\phi_m (m^2 / s)$	$\alpha^* (m^{-1})$
/ *	/
/ *	/
/ *	/
/ *	/
/ *	/
/	/
/	/
/	/

α^*

) α (m^{-1})

($\phi_m (m^2 / s)$ $\alpha (m^{-1})$)

α^*

α^*

ϕ_m

ϕ_m

ϕ_m

α^*

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