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(/ / , / / , / /)

()
(MOSS)
(ETS)

(JIT)

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) PMSP-E/T
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PMSP-E/T

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.....

s.t.

$$\begin{aligned} c_{i_N} + e_i - t_i &= d_i \quad \forall i \\ \sum_{i=0}^N \sum_{k=1}^K x_{ijk} &= 1 \quad \forall j \\ i \neq j \end{aligned} \quad ()$$

$$\sum_{i=0}^N x_{ijk} = y_{jk} \quad \forall j, k \quad ()$$

$$\sum_{j=1}^N x_{ijk} \leq y_{ik} \quad \forall i, k \quad ()$$

$$\sum_{k=1}^K y_{ik} = 1 \quad \forall i \quad ()$$

$$c_j - c_i + W(1 - x_{ijk}) \geq p_{jk} + s_{ijk} \quad \forall i, j, i \neq j \quad ()$$

$$c_i \geq s_{0ik} \times y_{ik} + p_{ik} \times y_{ik} \quad \forall i, k \quad ()$$

$$y_{ik} \in \{0,1\} \quad \forall i, k \quad ()$$

$$x_{ijk} \in \{0,1\} \quad \forall i, j, k; i \neq j \quad ()$$

$$c_i, t_i, e_i \geq 0 \quad \forall i \quad ()$$

j= (i n) ... :j i

(k= K) ... :K

i :c_i

i :t_i

i :e_i

i :d_i

i :beta_i

i :alpha_i

k :P_ik

j :S_ijk

k

:W

yjk :x_ijk

;

k j i } = x_ijk

k j } = B_v

()

()

n

k j m

()

k i ()

$$\min z_1 = \sum_{i=1}^N \alpha_i e_i$$

()

$$\min z_2 = \sum_{i=1}^N \beta_i t_i$$

()

$$\overline{x} \quad (\)$$

$$\delta > 0$$

$$\begin{array}{ccc} \vec{x}_1 & & (\) \\ \delta & \vec{x} & \vec{x} \\ & \vec{x} & (\) \end{array}$$

$$\begin{array}{ccc} & (\) & (\) \\ \vec{x}_1 & \vec{x} & (\) \\ \vec{x} & & \text{MOSS} \end{array}$$

$$\begin{array}{c} (\) \\ \quad \quad \quad) \\ \quad \quad \quad (\end{array}$$

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Surrogate constraint problem

$$(\quad)$$

$$\begin{array}{ccc} \vec{x}_2 & \vec{x}_1 & \\ f_i(\vec{x}_1) \leq f_i(\vec{x}_2) & & i=1,\dots,q \\ f_i(\vec{x}_1) \prec f_i(\vec{x}_2) & \exists & i=1,\dots,q \end{array} \quad (\)$$

ε

....

()

()

k n_k

n

()

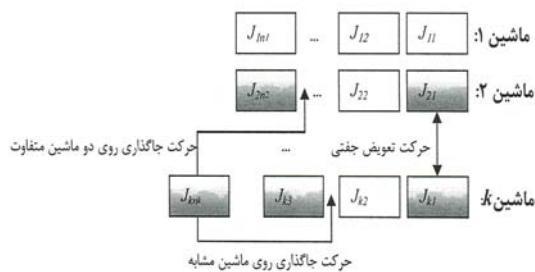
J_{1n1}	...	J_{12}	J_{1I}
J_{2n2}	...	J_{22}	J_{2I}

ماشین ۱ : J_{1I}
ماشین ۲ : J_{2I}

.....

J_{knk}	...	J_{k3}	J_{k2}	J_{kl}
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ماشین k : J_{kl}



کار انجام شده در موقعیت l از ماشین k تعداد کارهای انجام شده روی ماشین n_k

N

N

α

$\alpha \times N$

Lingo 8

$$\alpha \times N$$

$$N$$

$$N \alpha \times N$$

$$N_{j-1}^{j-1} \dots i^{i-1} \\ j-1 \dots i$$

$$k \times n^{1.5} / (m - 0.5)$$

$$l \dots k$$

$$\text{Lingo } 8$$

$$\zeta = \sum_{i=1}^k \frac{|f_i - F_i|}{w_i} \quad ()$$

$$i \quad f_i \quad ()$$

$$w_i \quad i \quad F_i$$

$$N \quad i$$

$$w_i$$

$$i$$

$$\eta$$

$$\eta = \zeta_B - \zeta_A \quad ()$$

$$B \quad A \quad ()$$

$$\eta \leq 0$$

$$A \quad B$$

$$\eta \leq 0$$

$$A \quad B \quad \text{Aspiration}$$

$$\eta \geq 0$$

$$A \quad B$$

$$A$$

$$\text{Arch-Size}$$

$$\eta \geq 0$$

$$A$$

()

landa

ماشين 1: 

ماشين 2: 

حل کمکی (۳-۱، ۲-۳، ۱-۴، ۳-۲، ۱-۵)

ماشين 1: 

ماشين 2: 

حل اولیه (۱-۲، ۳-۴، ۵-۲، ۱-۳)

ماشين 1: 

ماشين 2: 

حل مرحله ۳ (۳-۱، ۵-۱، ۲-۴-۳، ۱-۲)

ماشين 1: 

ماشين 2: 

حل نهایی (۳-۱، ۳-۲، ۱-۱، ۳-۱، ۴-۳)

ماشين 1: 

ماشين 2: 

حل مرحله ۱ (۳-۱، ۵-۱، ۲-۳، ۴-۱، ۱-۲)

ماشين 1: 

ماشين 2: 

حل مرحله ۳ (۳-۱، ۵-۱، ۲-۳، ۴-۲، ۱-۱)

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RefSet₂

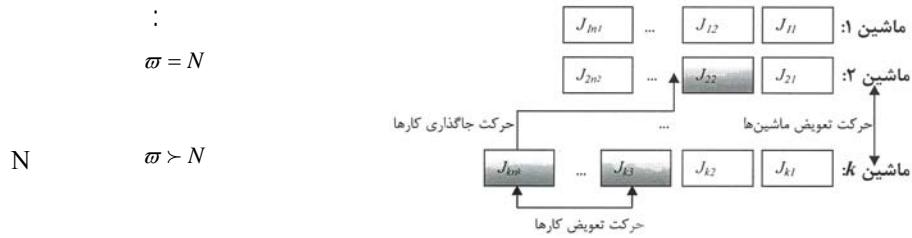
()

b*(b-1)/2

Mcuox

local-iteration

ω



$N - \sigma$

()

() RefSet₁
() RefSet₂
 $b_2 \quad b_1$
.Refset | = $b \leq b_1 + b_2$
 $b_1 \quad$ RefSet₁

RefSet₁

RefSet₁

b_2

Matlab 7

$$SUMP = \sum_{i=1}^m \left(\frac{\sum_{j=1}^n p_{ij}}{n} \right)$$

RD F ()

/ RD / F

()

l

xp

m n

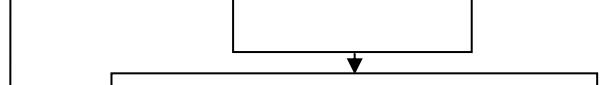
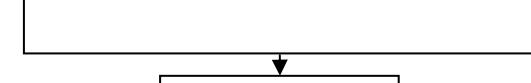
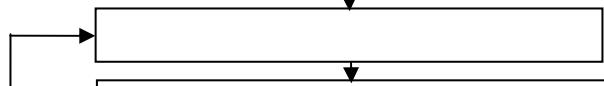
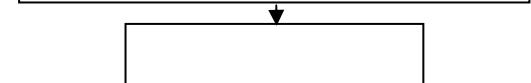
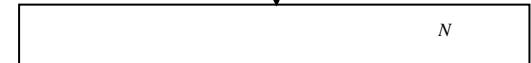
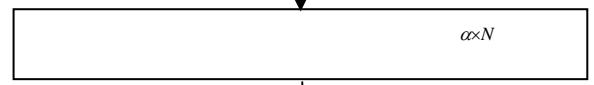
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spacing

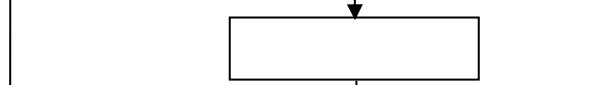
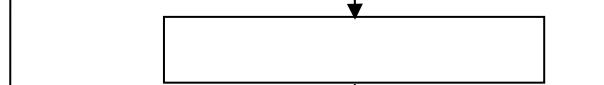
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Mcuox



$$S = \left[\frac{1}{n-1} \sum_{i=1}^n (\bar{d} - d_i)^2 \right]^{1/2}$$

d_i

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[,] :

[,] :

[,] :

\bar{d}

d_i

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[[SUMP/2](1-F-RD/2)] [[SUMP/2](1-F+RD/2)]]

$$D = \sqrt{\sum_{i=1}^n \max \left(\|x_t^i - y_t^i\| \right)}$$

$$\|x_t^i - y_t^i\|$$

$$x_t^i - y_t^i$$

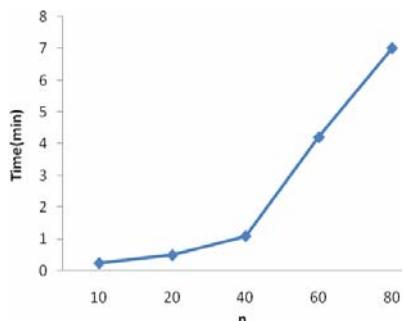
m	n	
2	10	1
4	10	2
2	20	3
4	20	4

		spacing				
		ETS	MOS S			
58.11	302.5	385	77. 4	9.2	21.5	1
24.9	116.1	85. 5	14. 4	10.8	30.7	2
100.6	326.5	806	382	12.6	76.3	3
68.06	149.3	313	112	12.2	68.8	4

N ➤
 ϵ ➤
 Arch_Size ➤
 landa ➤
 $b_2 - b_1$ ➤

m	n	
4	40	1
6	40	2
4	60	3
6	60	4
4	80	5
6	80	6

()



Arch_Size

N

➤

➤

ε

➤

landa

➤

b₂ b₁

➤

()

()

		spacing				
E _T S	MOS _S	E _T S	MOS _S	E _T S	MOS _S	
177.3	150	1327	158	9.4	153	1
135.7	189	601	30	18.5	122	2
184	284	1034	679	18.9	143	3
90.8	212	1200	68	16.4	114	4
275.7	362	278	129	6.1	189	5
240.4	258	1499	471	18.3	103	6

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- 1 - Unrelated Parallel Machines
3 - Multi-Objective Scatter Search
5 - Just-In-Time
7 - Pareto Archive
9 - Multi-Component Uniform Order-Based Crossover

- 2 - Sequence-Dependent Setup Times
4 - Elite Tabu Search
6 - Non-Dominated Solutions
8 - Dynamic Ideal Point